



PATENT  
ATTORNEY DOCKET NO.: 046601-5053



IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Commissioner for Patents  
**BOX PATENT APPLICATION**  
Washington, D.C. 20231

**TRANSMITTAL FOR A NEWLY EXECUTED ORIGINAL APPLICATION  
UNDER 37 C.F.R. §1.53(b)**

This is a request for filing a patent application under 37 C.F.R. §1.53(b) for:

Inventors: Masayoshi OKURA, Takahiko KOBAYASHI, Tehli SHAO and Masahiko OTSU

For: ROTARY DEFLECTOR, OPTICAL SCANNING UNIT AND IMAGE FORMING  
APPARATUS

1. This is a new ☒ **Utility** ☐ **Design** ☐ **Plant** patent application.
2. The papers enclosed to obtain a filing date are as follows:
  - 17 Pages of Specification including
  - 0 Title Page
  - 2 Pages of Claims
  - 1 Page of Abstract
  - 26 Sheets of drawings containing 39 Figures
  - ☐ The enclosed drawing(s) are photograph(s), and there is also attached a PETITION TO ACCEPT PHOTOGRAPH(S) AS DRAWING(S)
3. Combined Declaration and Power of Attorney
  - ☒ Enclosed and is executed by all inventors.
  - ☐ Not Enclosed.

This application is being filed under the provisions of 37 C.F.R. §1.53(f).  
Applicant(s) await notification from the Patent and Trademark Office of the time  
set for filing the Declaration and paying the filing fees.

## 4. Language

☒ English☐ Non-English

This application is being filed in accordance with 37 C.F.R. §1.52(d) and §608.01 of the MPEP. Applicant(s) await notification from the Patent and Trademark Office of the time set for filing the verified English translation and the processing fee.

## 5. Assignment

☒ An assignment of the invention to FUJIXEROX CO., LTD. and a PTO Form-1595, Recordation Form Cover Sheet, are enclosed.☐ An assignment will be filed at a later date.

## 6. Priority - foreign applications under 35 U.S.C. §119(a)-(d) or §365(b) or PCT international applications under 35 U.S.C. §365(a) designating at least one country other than the U.S.

☒ Priority of the following foreign application is claimed:

Country	Application No.	Filed
Japan	11-255592	September 9, 1999

Certified copy: ☒ is attached. ☐ will follow.

## 7. Priority based on provisional application(s) - 35 U.S.C. §119(e)

☐ Priority of the following provisional application(s) is claimed:

Application No.	Filed

## A. Relate Back - 35 U.S.C. §119(e)

- ☐ Amend the specification by inserting before the first line the sentence:  
 "This application claims priority of copending provisional application(s)  
 No. \_\_\_\_\_ filed on \_\_\_\_\_."

## 8. Small entity status

- ☐ A statement claiming small entity status under 37 C.F.R. §§1.9 and 1.27 is enclosed.

## 9. Fee Calculation (37 C.F.R. §1.16)

CLAIMS FOR FEE CALCULATION				
	Number Filed	Number Extra	at Rate of	Basic Fee Utility \$690.00 Design \$310.00
Total Claims (37 C.F.R. §1.16(c))	12 - 20 =	0	\$ 18.00 each=	\$0.00
Independent Claims (37 C.F.R. §1.16(b))	3 - 3 =	0	\$ 78.00 each=	\$0.00
Multiple dependent claim(s), if any (37 C.F.R. §1.16(d))			\$260.00	+
SUB-TOTAL =				\$690.00
Reduction by 1/2 for filing by a small entity				- \$
TOTAL FILING FEE =				\$690.00

## 10. Fee Payment

- ☐ Not Enclosed. **NO FEE IS BEING PAID BY CHECK OR DEPOSIT ACCOUNT AT THIS TIME.**  
 This application is being filed under the provisions of 37 C.F.R. §1.53(f).  
 Applicant(s) await notification from the Patent and Trademark Office of the time set for filing the Declaration and paying the filing fees.

[X] Enclosed.

Two checks in the amounts of \$ 690.00 and \$40.00 representing the basic filing fee of \$690.00 and an assignment recording fee of \$40.00 are enclosed.

11. [X] **Except** for issue fees payable under 37 C.F.R. §1.18, the Commissioner is hereby authorized by this paper to charge any additional fees during the entire pendency of this application including fees due under 37 C.F.R. §§1.16 and 1.17 which may be required, including any required extension of time fees, or credit any overpayment to Deposit Account 50-0310. This paragraph is intended to be a **CONSTRUCTIVE PETITION FOR EXTENSION OF TIME** in accordance with 37 C.F.R. §1.136(a)(3).

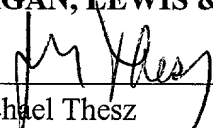
12. Additional papers enclosed:

- [ ] Preliminary Amendment
- [X] Information Disclosure Statement
- [X] Form PTO-1449, 1 document included
- [ ] Declaration of Biological Deposit
- [ ] Submission of "Sequence Listing", computer readable copy and/or amendment pertaining thereto for biotechnology invention containing nucleotide and/or amino acid sequence.

**Please accord this application an application number and filing date.**

Respectfully submitted,

**MORGAN, LEWIS & BOCKIUS LLP**

  
\_\_\_\_\_  
J. Michael Thesz  
Reg. No. 40,354

Dated: July 11, 2000

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# ROTARY DEFLECTOR, OPTICAL SCANNING UNIT AND IMAGE FORMING APPARATUS

## BACKGROUND OF THE INVENTION

### Field of the Invention:

The present invention relates to a rotary deflector, an optical scanning unit and an image forming apparatus for use in a laser printer, a digital copier and the like.

### Related Art:

An optical scanning unit is provided with a driving motor for rotating a polygon mirror at high speed. However, it is unable to realize a high image quality because optical parts vibrate, scanning position deviates periodically and nonuniformity of pitch occurs on an image unless vibration caused by the driving motor is reduced. Still more, noise may be generated when a housing of the optical scanning unit resonates with a base of the image forming apparatus.

In order to eliminate such a problem, Japanese Patent Laid-Open No. Hei. 5-264916 has disclosed a method of controlling the resonating condition of the housing by changing fixing points of the base and the housing of the image forming apparatus per type of machine or by increasing/reducing a mass element to be added to the housing, to avoid the resonance frequency of the housing in correspondence to changes of vibrating frequency of a source of vibration.

However, there has been a problem that when the fixing points of the housing are changed, the position of a laser beam fluctuates and the image quality degrades because the amount and the mode of deformation of the housing change.

The driving motor for rotating the polygon mirror is arranged so as to switch the rotational speed during the standby state and the image forming time to reduce

power consumption and to switch the rotational speed corresponding to an image density in order to accommodate to plural image densities (resolutions).

However, because the above-mentioned prior arts have had no arrangement of reducing the vibration of the vibrating source itself, there has been a problem that when the rotational speed is changed, the vibrating frequency of the driving motor approaches to the vibrating frequency of the housing, thus resonating and causing noise.

### SUMMARY OF THE INVENTION

The present invention has been made in order to solve the above-mentioned problem and reduces noises and stabilizes the image quality by reducing vibration of the image forming apparatus by reducing vibration of the driving source itself within a preset frequency range without changing the resonating condition of the housing.

According to an aspect of the invention, a mass member is attached to a non-driving section of a driving motor for rotating a polygon mirror. It then becomes possible to avoid the resonance and to reduce vibration and noise by moving a resonance point by adding the mass member to the non-driving section.

For instance, it is possible to reduce the noise by attaching the mass member to a stationary shaft which is located at the center of rotation of the driving motor and which is considered to be the non-driving section.

The specific nature of the invention, as well as other objects, uses and advantages thereof, will clearly appear from the following description and from the accompanying drawings.

### BRIEF DESCRIPTION OF THE DRAWINGS

Preferred embodiments of the present invention will be described in detail based on the following figures, wherein:

FIG. 1 is a plan view showing an optical scanning unit provided with a rotary deflector of a first embodiment;

FIG. 2 is an exploded perspective view of the rotary deflector according to the first embodiment;

FIG. 3 is a sectional view of the rotary deflector of the first embodiment;

FIG. 4 is a plan view of the rotary deflector of the first embodiment;

FIG. 5 is a graph showing the relationship between vibration of a base and noise;

FIG. 6 is a graph showing the vibration level of a driving motor when no mass member is attached;

FIG. 7 is a graph showing the vibration level of the driving motor when the mass member is attached;

FIG. 8 is a graph showing the vibration level of the housing when no mass member is attached;

FIG. 9 is a graph showing the vibration level of the housing when the mass member is attached;

FIG. 10 is a graph showing the vibration level of the base when no mass member is attached;

FIG. 11 is a graph showing the vibration level of the base when the mass member is attached;

FIG. 12 is a graph showing the vibration level of the base when a quantity of unbalance of the driving motor is increased and no mass member is attached;





gravity and the resonance frequency of the base;

FIG. 25 is a plan view of a rotary deflector according to a third embodiment;

FIG. 26 is a sectional view of the rotary deflector of the third embodiment;

FIG. 27 is a plan view of the rotary deflector of the third embodiment;

FIG. 28 is a graph showing the relationship between the mass member and the chattering noise;

FIG. 29 is a plan view of the rotary deflector of the fourth embodiment; and

FIG. 30 is a sectional view of the rotary deflector of the fourth embodiment.

#### DESCRIPTION OF THE PREFERRED EMBODIMENTS

An optical scanning unit provided with a rotary deflector of a first embodiment will be explained below with reference to the drawings.

(Schematic Structure of Optical Scanning Unit)

As shown in FIGs. 1 through 4, a housing 16 of the optical scanning unit 14 is formed of synthetic resin and is attached to a base 18 of an image forming apparatus by four fixing screws 12. The fixing points of the fixing screws 12 are always fixed and are not shifted depending on types of machine. Therefore, the amount and the mode of deformation of the housing 16 restricted by the fixing screws 12 are uniform and the position of the laser beam does not fluctuate per type of machine, thus causing no degradation of image quality.

An upper opening of the housing 16 is almost closed by a cover (not shown) and optical parts are stored in the concealed space.

In the optical system including such optical parts, a laser beam emitted out of a laser diode 10 is collimated by a collimator lens 18, shaped by a slit 20, reflected by a reflecting mirror 22 and arrives at a polygon mirror 24 composing a rotary deflector 31

via Fθ lenses 26 and 28. The polygon mirror 24 is a polygonal column having plural mirrors on the side faces thereof and is rotated at high speed by a driving motor 30.

The laser beam obtains a swing angle by being deflected by the polygon mirror 24, passes through the Fθ lenses 26 and 28 again, reflected by a mirror 34 and a cylindrical mirror 200, and performs scanning on a photoreceptor (not shown).

It is noted that a quantity of emission and emitting time of the laser diode 10 are controlled by a laser diode driver substrate. It modulates the laser diode 10 corresponding to image signals from the main body side to record an image on the photoreceptor.

Further, an SOS sensor 32 receives the laser beam reflected by a pickup mirror 36 disposed at the position before the image forming area of the photoreceptor, which is irradiated with the laser beam at first, to decide image writing timing.

Next, the rotary deflector will be explained.

As shown in FIGs. 2 and 3, a base plate 38 of the driving motor 30 provided in the rotary deflector 31 is fixed to the bottom of the housing 16 by fixing screws 40. A cylindrical stationary shaft 44 is fitted into a concave 42 formed at the center of the base plate 38 so as to stand straight.

A long screw 46 is inserted into a through hole of the stationary shaft 44. The long screw 46 penetrates the concave 42 and is screwed into a nut 50 fitted from the back of the base plate 38. Thereby, the stationary shaft 44 is fixed to the base plate 38 so as to stand straight from the top and bottom between the head 48 of the long screw 46 and the concave 42 via a washer 52.

A rotary sleeve 54 whose inner diameter is slightly larger than the outer diameter of the stationary shaft 44 is inserted into the stationary shaft 44 so as to be rotatable about the stationary shaft 44. It is noted that multiple dynamic pressure

generating grooves (not shown) are formed on the outer peripheral face of the stationary shaft 44 at a slant to the axial direction by a certain angle.

A flange 56 is attached to the rotary sleeve 54 and the polygon mirror 24 is attached to the flange 56 coaxially with the rotary sleeve 54.

The flange 56 is provided with a thrust bearing magnet 58 and a driving magnet 60. A magnetic material 62 is disposed on the base plate 38 so as to face to the side of the thrust bearing magnet 58 so that the rotary sleeve 54 does not move up and down by its magnetic action. A driving coil 64 is disposed on the base plate 38 to rotate the polygon mirror 24 at predetermined rotational speed by generating repulsive force and attractive force between the driving magnet 60 and the driving coil 64 by supplying alternating current whose phase is shifted.

Meanwhile, a screw hole 66 is formed at the axial center of the head 48 of the long screw 46 so as to be able to screw in a fixing screw 68. A step 70 is formed around the periphery of the head 48 so as to support a mass member 72 when an attaching hole 74 formed at the center of gravity of the mass member 72 is inserted into the head 48. That is, the mass member 72 may be fixed to the head 48 of the stationary shaft 44 by the fixing screw 68 via a washer 76 and a spring washer 77 without disassembling the stationary shaft 44. Therefore, it is possible to attach/remove the mass member having different mass in response to fluctuation of vibrating frequency and to realize a low noise and high image quality image forming apparatus by suppressing the vibration of the base 18 in a target frequency range.

The mass member 72 is formed of a square iron plate so as to be able to obtain the necessary mass with a small volume. The mass member 72 is symmetrical centering on the center of gravity thereof and its deflection from the center of gravity is constant. Also, the stationary shaft 44 will not fall when the mass member 72 is

attached to the stationary shaft 44, by causing the center of gravity of the mass member 72 to coincide with the center of axis of the stationary shaft 44.

The mass member 72 may also be inserted into the hollow section of the stationary shaft 44 instead of fixing it at the head 48 of the stationary shaft 44.

FIG. 5 shows the relationship between the vibration level of the base 18 and noise when the optical scanning unit 14 in which the mass member 72 (mass: 50 g) is attached to the stationary shaft 44 is mounted on the base 18 of the image forming apparatus. Here, the value of vibration (mV) is what acceleration is transformed into voltage and  $1000 \text{ mV} = 9.8 \text{ m/s}^2$  (acceleration).

While the vibration of the base 18 is caused by transmission of an exciting force due to unbalance of the driving motor 30 via the housing 16 of the optical scanning unit 14, the sound pressure level may be lowered to 52 dB or less and noise may be reduced by reducing the value of vibration to 50 mV or less.

It is thus possible to reduce the level of vibration and to reduce the noise by avoiding the resonance by moving the resonance point by attaching the mass member 72 to the stationary shaft 44 of the driving motor 30 in this embodiment.

FIGs. 6 and 7 show the result of comparison of vibration levels in the case where the mass member 72 is not attached and in the case where it is attached. The vibration in the vertical direction (the thrust direction of the stationary shaft 44) was measured at the fixing section of the base plate 38 of the rotary deflector 31 as the measuring point.

Then, the vibration level was measured by changing the rotational speed of the driving motor 30 from 250 Hz to 400 Hz. As a result, while the vibration level was 300 mV when there was no mass member as shown in FIG. 6 when the rotational speed was 340 Hz in forming an image, it was reduced to 65 mV when the mass

member was attached. Thus, it was possible to prevent noise from occurring in switching the speed of the rotary deflector.

The image forming apparatus of this embodiment is a printer which is adaptable to two kinds of resolution of 600 DPI and 480 DPI. The rotational speed of the polygon mirror 24 in printing in 600 DPI is 340 cycles per second and the rotational speed of the polygon mirror 24 in printing in 480 DPI is 272 cycles per second. Graphs in FIGs. 8 and 9 show the result in the range of rotational speed in use (272 Hz to 340 Hz). When the vibration at the center of the housing 16 was measured, the vibration level was reduced to 10 mV when the mass member was attached as compared to the case of 60 mV in maximum when no mass member was attached.

FIGs. 10 and 11 show the comparison of vibration levels of the base 18. The measuring point was the center of four fixing points where the housing 16 shown in FIG. 1 is fixed by the fixing screws 12. While the vibration level was 340 mV in maximum when no mass member was attached, it was reduced to 20 mV when the mass member was attached.

The unbalance of the driving motor 30 used in the rotary deflector of this embodiment conforms to a specification requiring G2 (JISB0905: grade of balance of rotary device).

FIGs. 5 through 11 show the results of measuring the unbalance of the driving motor 30 confirmed on the level of G2. Graphs in FIGs. 12 and 13 show the results of measuring the vibration of the base 18 when the degree of unbalance of the driving motor 30 is intentionally increased to G6.

According to this measured result, while the vibration level was 680 mV in maximum when no mass was attached, it was reduced to 20 mV or less when the mass

member was attached and the unbalance was reduced to the level of G2. Thus, the vibration does not change due to a drift of balance, so that it is possible to realize low vibration design in a short time, improving the reliability.

Although most of the unbalance of the driving motor of mass-produced products is normally controlled in the level of G1 through G3, it is possible to considerably relax balance specifications, to reduce balancing processes and to reduce the cost considerably.

Next, the relationship between the mass of the mass member and the resonance frequency will be explained.

The resonance point moves downward stepwise, as shown in FIG. 14A in which the resonance point is 400 Hz when no mass member is attached, in FIG. 14B in which the resonance point is 220 Hz when the mass member is 25 g, in FIG. 14C in which the resonance point is 155 Hz when the mass member is 50 g, in FIG. 14D in which the resonance point is 140 Hz when the mass member is 65 g, in FIG. 14E in which the resonance point is 130 Hz when the mass member is 75 g, and in 14F in which the resonance point is 110 Hz when the mass member is 85 g.

Thus, it becomes possible to achieve optimal tuning to lower the vibration per type of machine and to be readily adaptable to other type machines just by selecting the mass of the mass member.

FIGs. 15 and 16 show a rotary deflector of a second embodiment.

A mass member 80 is formed of a rectangular iron plate. An attaching hole 82 formed at the center of gravity of the plate is inserted into the head 48 of the long screw 46 and is fixed by the fixing screw 68. Hook pieces 80A are bent downward at both ends of the mass member 80 in the longitudinal direction and are positioned between ribs 84 for reinforcing the housing 16. Even if the fixing screw 68 for fixing



of 75 g at 66 % to concentrate the weight further.

It is thus possible to reduce the vibration level of the base 18 by concentrating the ratio of weight of the mass member on the axial center of the stationary shaft as it may be judged from a graph shown in FIG. 22. It is noted that this experimental result shows maximum values in the range of the rotational frequency in use of 170 Hz to 340 Hz and the vibration level is stabilized by concentrating the weight ratio to 46 % or more. However, when the weight ratio is concentrated up to 57 %, no problem occurs even when there is dispersion (3 % in maximum) due to mass-production. It is noted that the mass members 86, 90, 92 and 94 are provided with hooks 86A, 90A, 92A and 94A whose rotation is stopped by the rib 84 of the housing 16.

FIG. 23 shows the relationship between the mass of the mass member and the resonance point.

As it is apparent from FIG. 23, the dispersion of the resonance point of the base 18 is reduced to 20 Hz or less and the effect of the present invention may be brought about by increasing the mass of the mass member to 5 g or more.

FIG. 24 shows the relationship between the gravitational position of the mass member acting in the axial direction of the driving motor and the resonance frequency of the base. As shown in the graph, the gravitational position of the mass member is also one of important parameters deciding the resonance point.

Next, a rotary deflector of a third embodiment will be explained.

As shown in FIGs. 25 and 26, a sheet-like foaming sponge 98 is pasted as an elastic member on the both faces of the inside of the rib 84 and the hook 80A of the mass member 80 is positioned in the foaming sponge 98. It has been confirmed that when the hook 80A is pressed lightly or strongly against the foaming sponge 98 as



shown in FIG. 27, no chattering noise occurs as shown in a graph in FIG. 28. Thus, the inclusion of the foaming sponge 98 allows to prevent such chattering noise from occurring that may occur when without foaming sponge 98 the hook 80A contacts with the rib 84.

Next, a rotary deflector of a fourth embodiment will be explained.

According to the fourth embodiment, a disk-like mass member 104 is integrally formed with a stationary shaft 102 at the upper part thereof. A long screw 100 is inserted through a penetrating section of the stationary shaft 102 and is fastened to a nut 50 by turning a head 106 thereof by a driver.

Thus, the rigidity of the stationary shaft increases and it becomes advantageous from the aspect of attaching space and production cost by integrally forming the stationary shaft with the mass member.

It is noted that although the housing has been made of synthetic resin in the embodiments described above, the vibration may be reduced further when the housing is made of aluminum whose rigidity is higher.

As described above, the invention allows the low noise and high image quality image forming apparatus to be realized by suppressing the vibration of the base in the target frequency range without deforming the housing. It also allows to prevent noise from occurring in switching the speed of the rotary deflector.

Still more, the optical scanning units may be made common because the reduction of vibration may be optimized by the mass member. It is also possible to achieve optimal tuning to lower vibration per each type machine and to reduce the balancing processes of the driving motor considerably by selecting the mass member.

While the preferred embodiments have been described, variations thereto will occur to those skilled in the art within the scope of the present inventive concepts

which are delineated by the following claims.

NOT RECORDED

What is Claimed is:

1. A rotary deflector wherein a mass member is attached to a non-rotary section of a driving motor for rotating a polygon mirror.
2. The rotary deflector according to Claim 1, wherein the non-rotary section is a stationary shaft located at the center of rotation of the driving motor and the mass member is attached to the stationary shaft.
3. The rotary deflector according to Claim 2, wherein the center of gravity of the mass member is located almost at the center of the stationary shaft.
4. The rotary deflector according to Claim 2, wherein the mass member is a plate-like member and is symmetrical about the center of gravity.
5. The rotary deflector according to Claim 2, wherein the mass member of a size capable of reducing vibration within the range of the number of rotation of the driving motor is attached.
6. The rotary deflector according to Claim 5, wherein the weight of the mass member is 5 g or more.
7. The rotary deflector according to Claim 2, further comprising:  
an engaging section formed at the upper part of the stationary shaft;  
an engaged section which is formed at the center of gravity of the mass member and which engages with the engaging section; and  
a fixing unit that fixes the engaged section and the engaging section.
8. The rotary deflector according to Claim 1, wherein the mass member is formed integrally with the stationary shaft.
9. An optical scanning unit comprising:  
a rotary deflector, wherein a mass member is attached to a non-rotary section of a driving motor for rotating a polygon mirror.



### ABSTRACT OF THE DISCLOSURE

The inventive device reduces noises and stabilizes the image quality of an image forming apparatus by reducing vibration thereof by reducing vibration of a driving source itself within a preset frequency range without changing the resonating condition of a housing. A mass member is added to a stationary shaft of a driving motor for rotating a polygon mirror. It then becomes possible to reduce the vibration and noise of an image forming apparatus by avoiding resonance by moving a resonance point by adding the mass member to the stationary shaft. Thus, a high image quality image forming apparatus can be realized.

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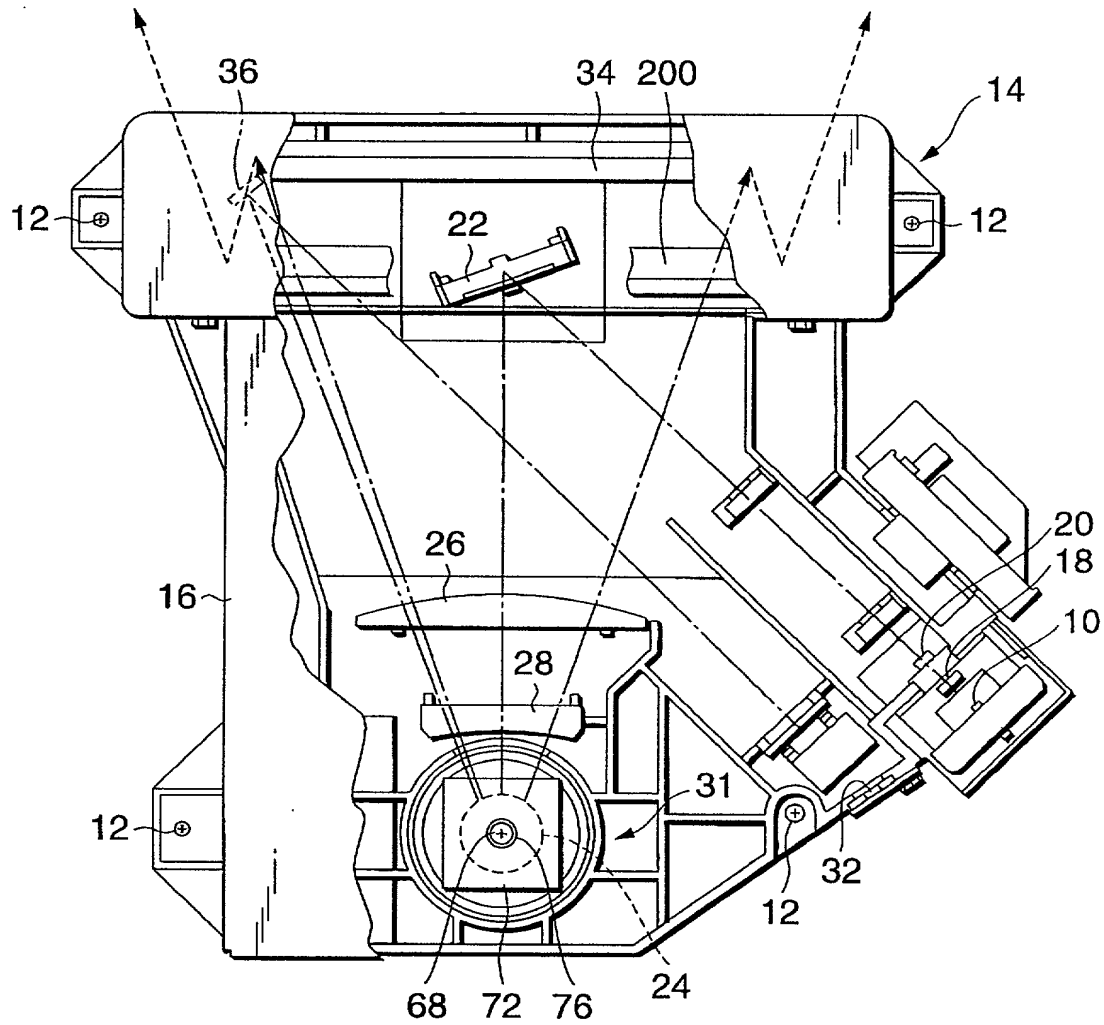


FIG.2

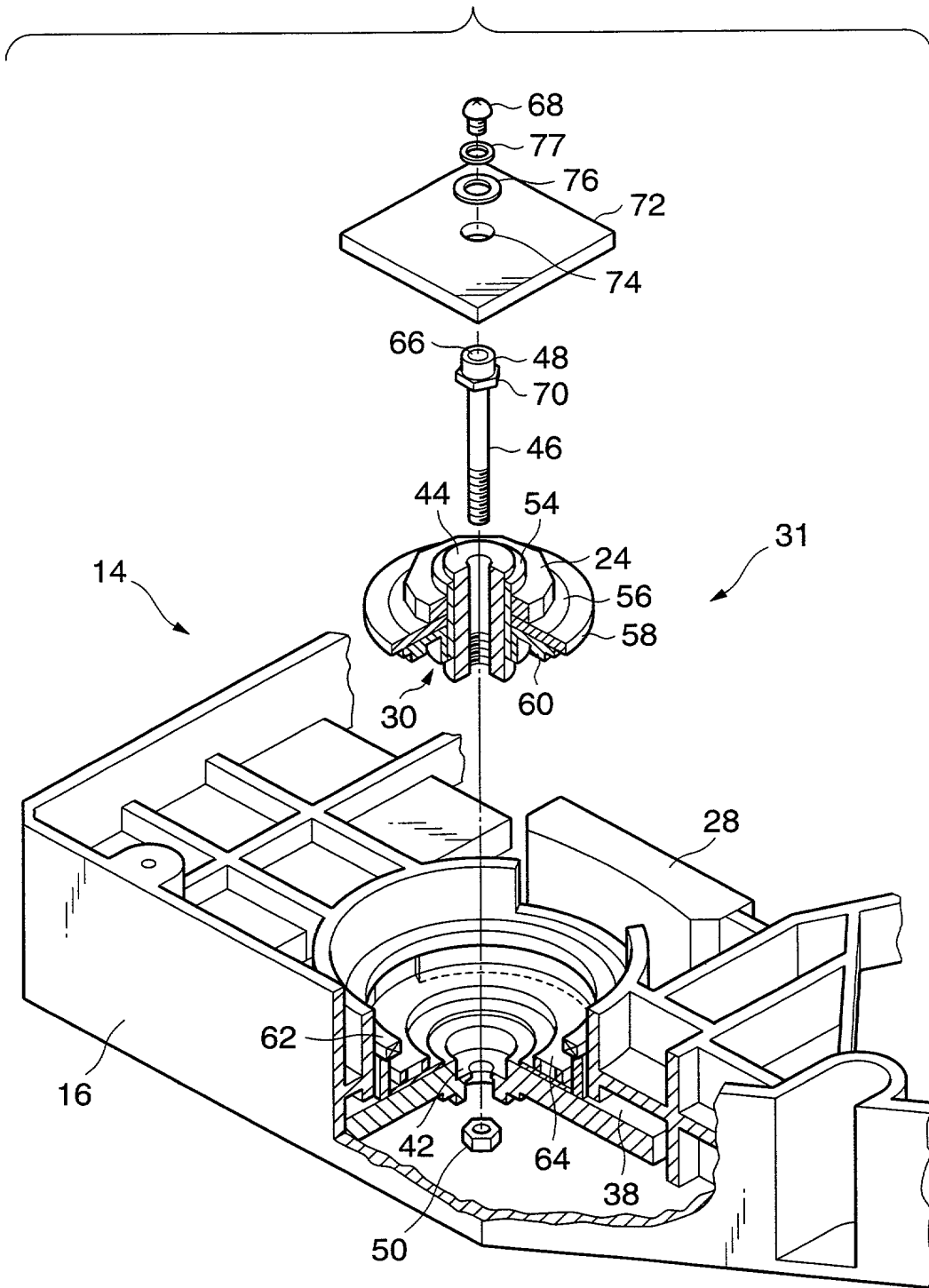


FIG.3

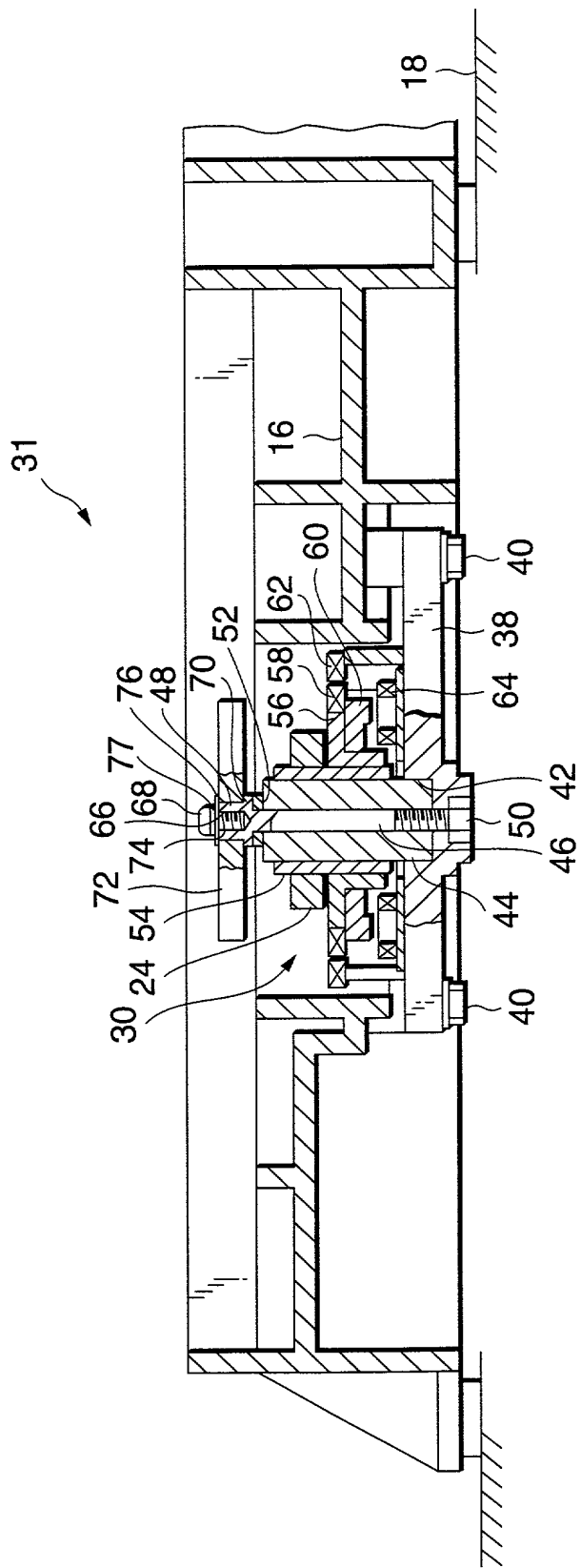




FIG.4

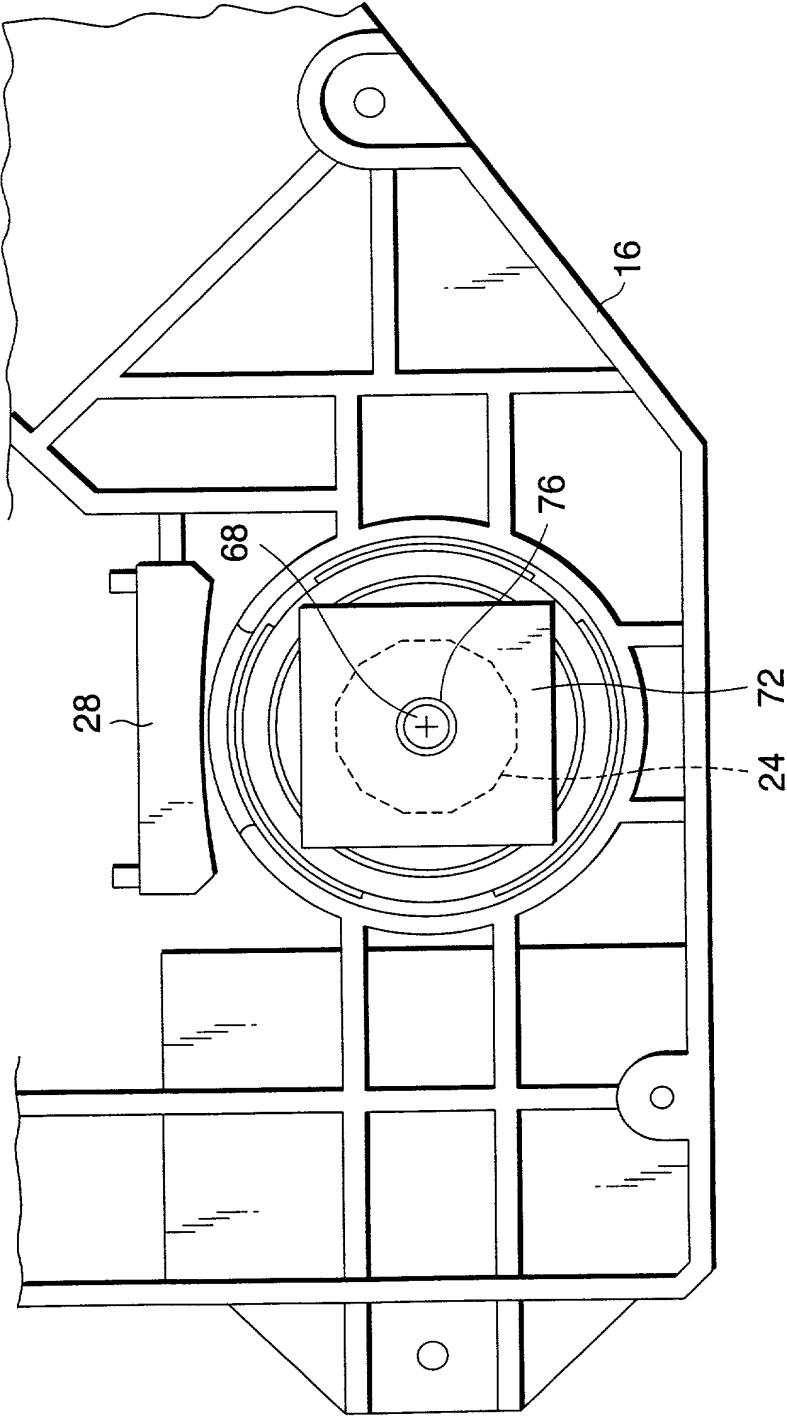


FIG.5

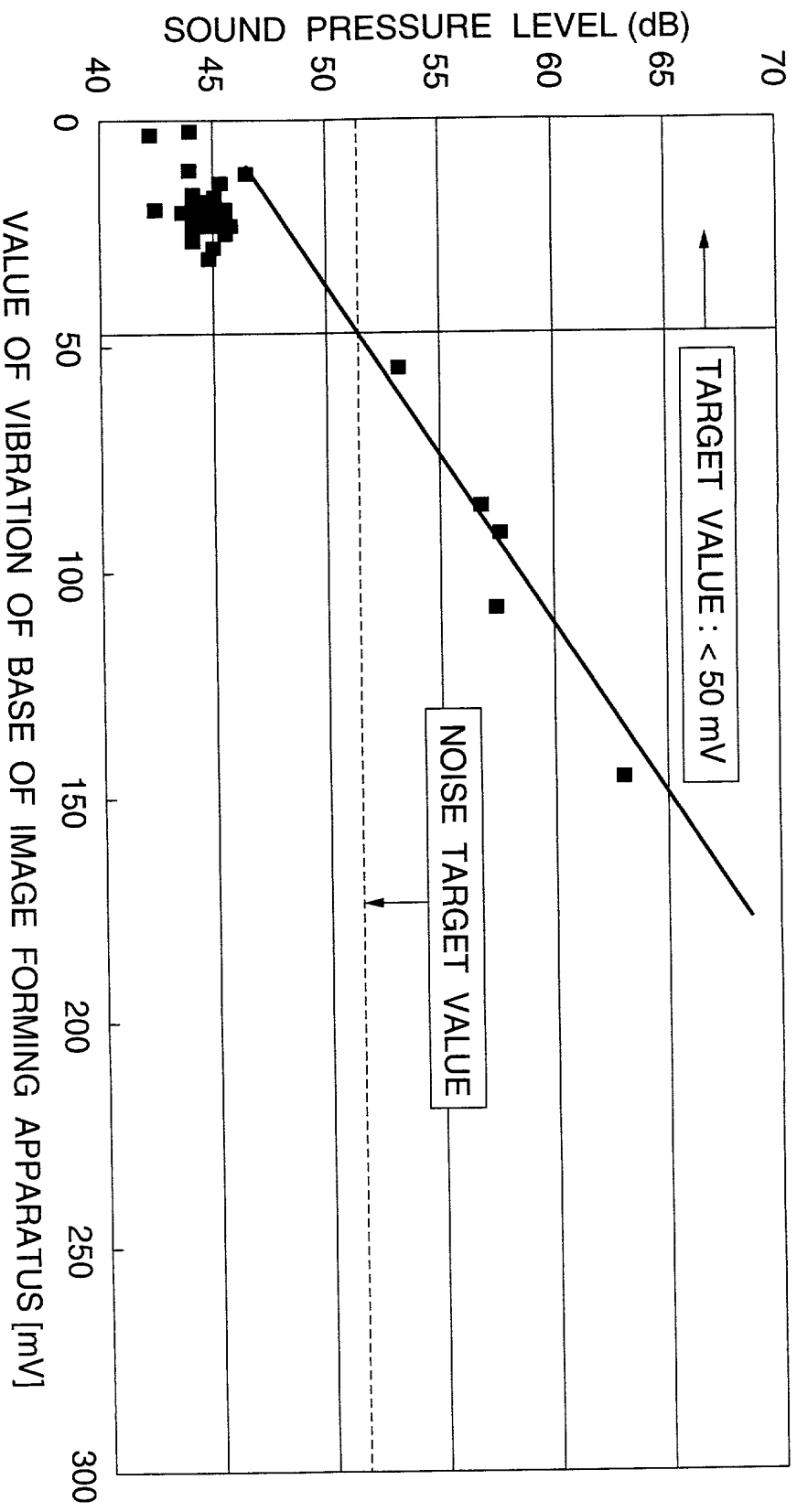


FIG.6

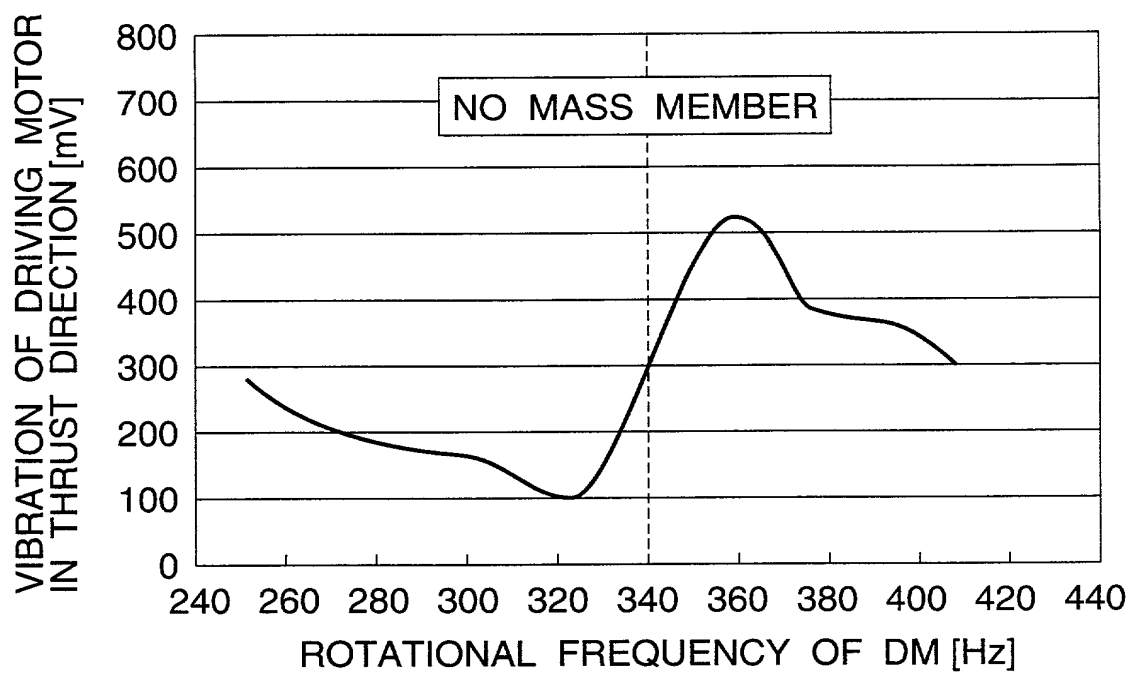
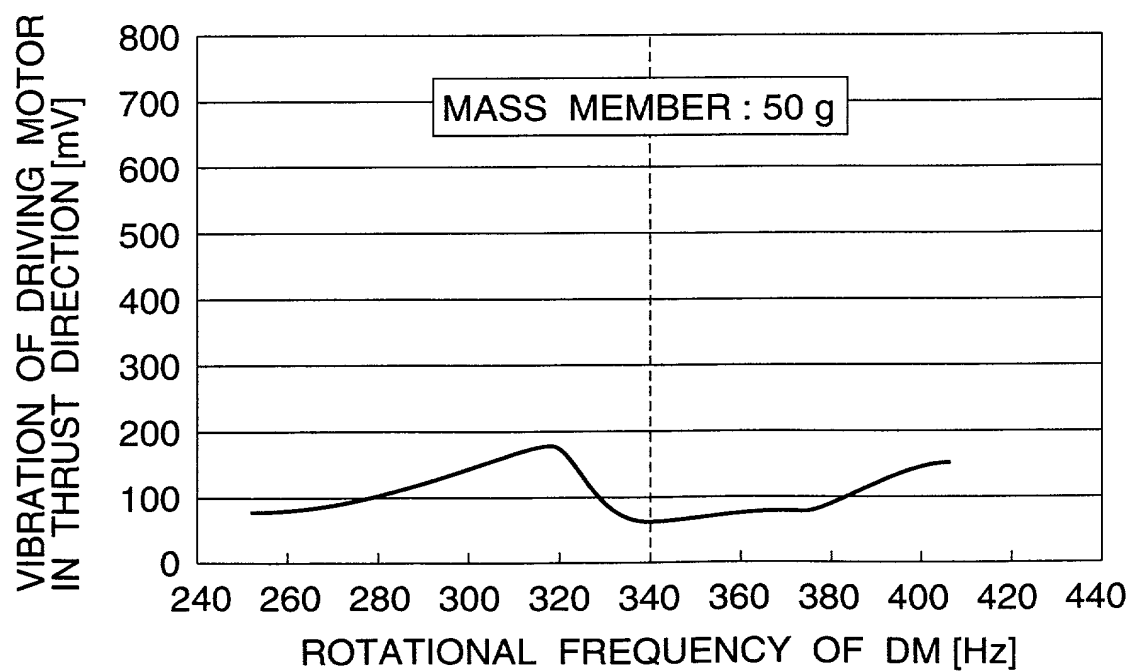


FIG.7



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FIG.8

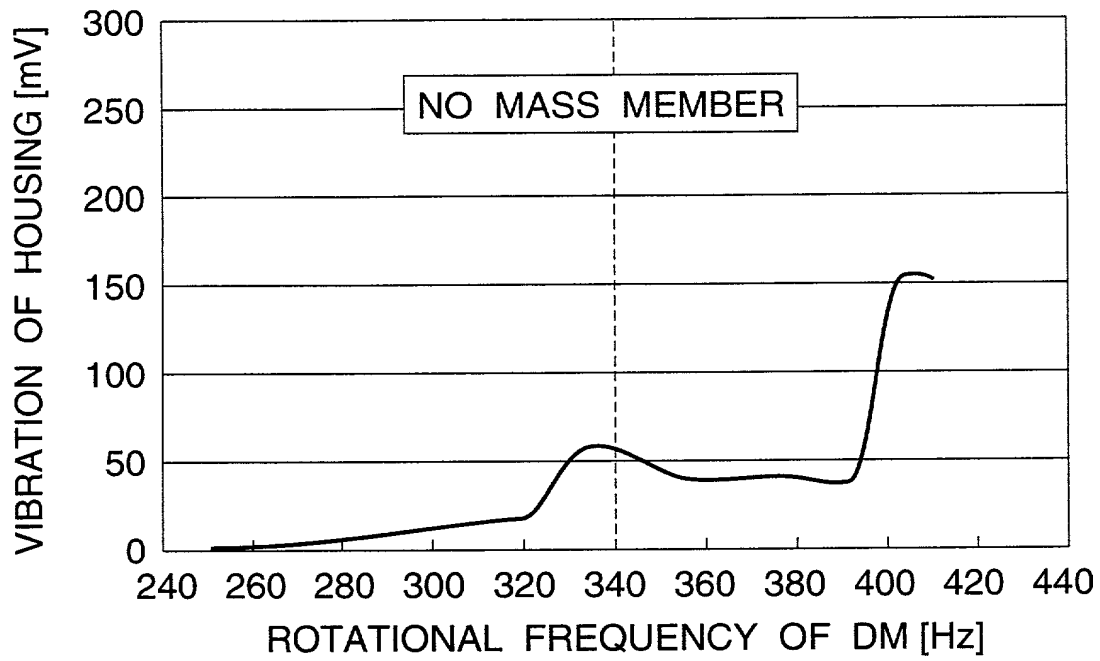


FIG.9

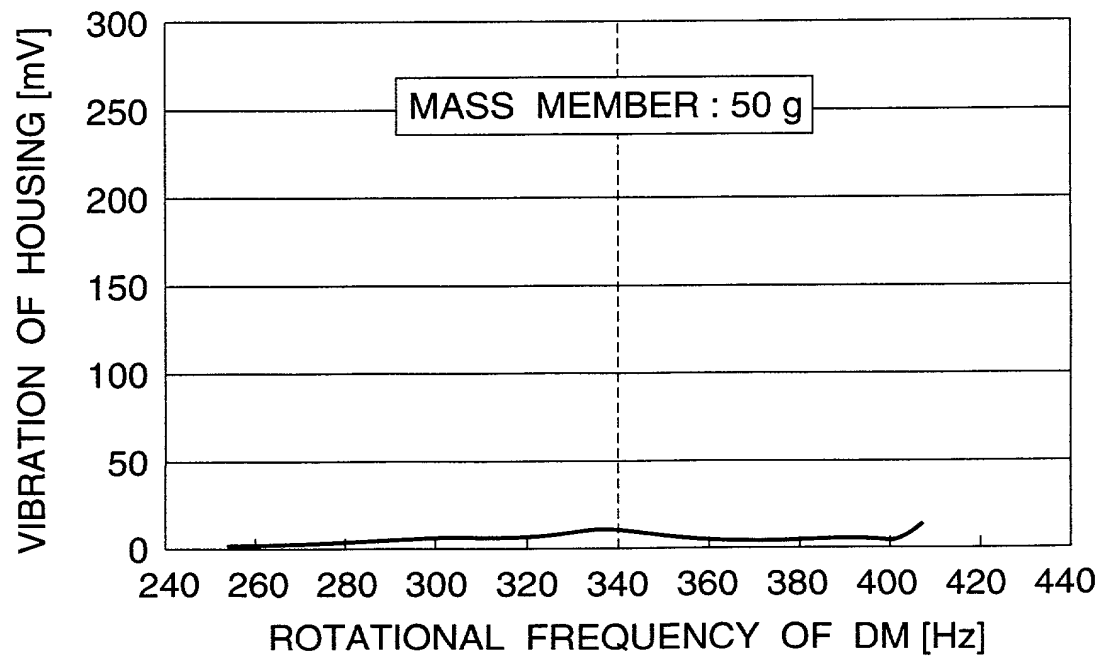


FIG.10

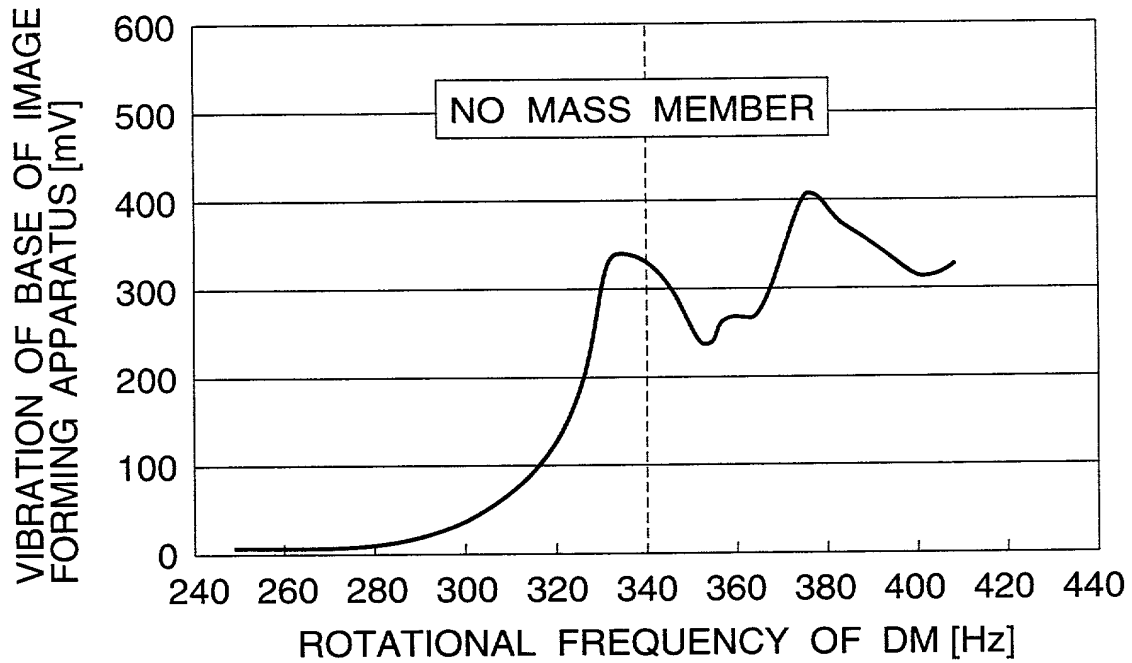
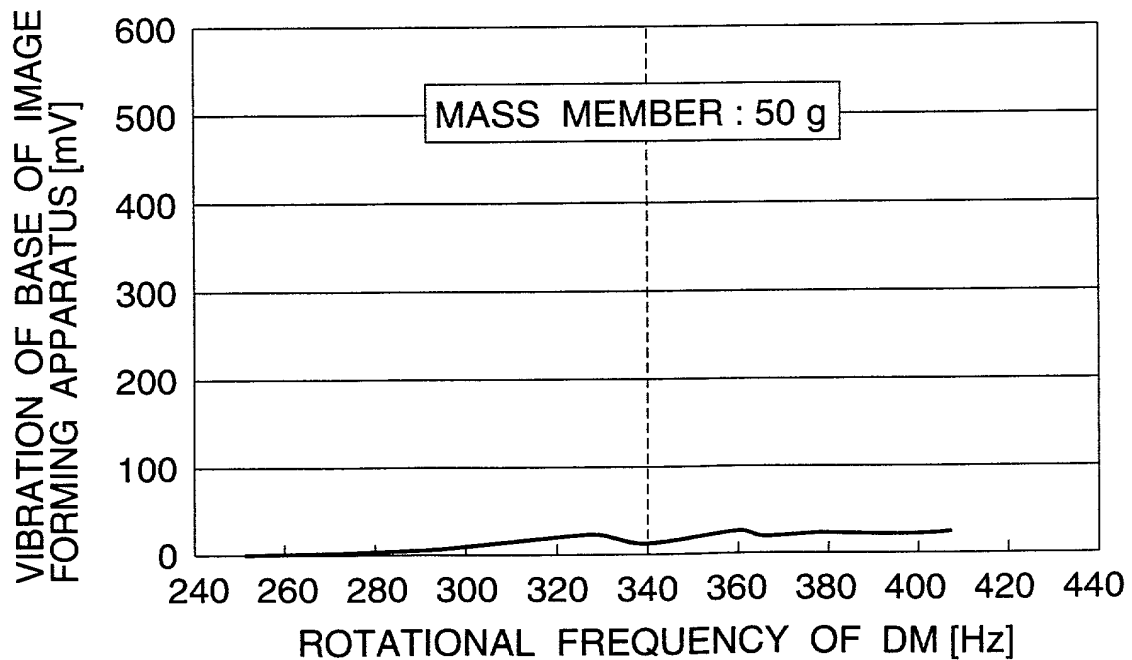


FIG.11



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FIG.12

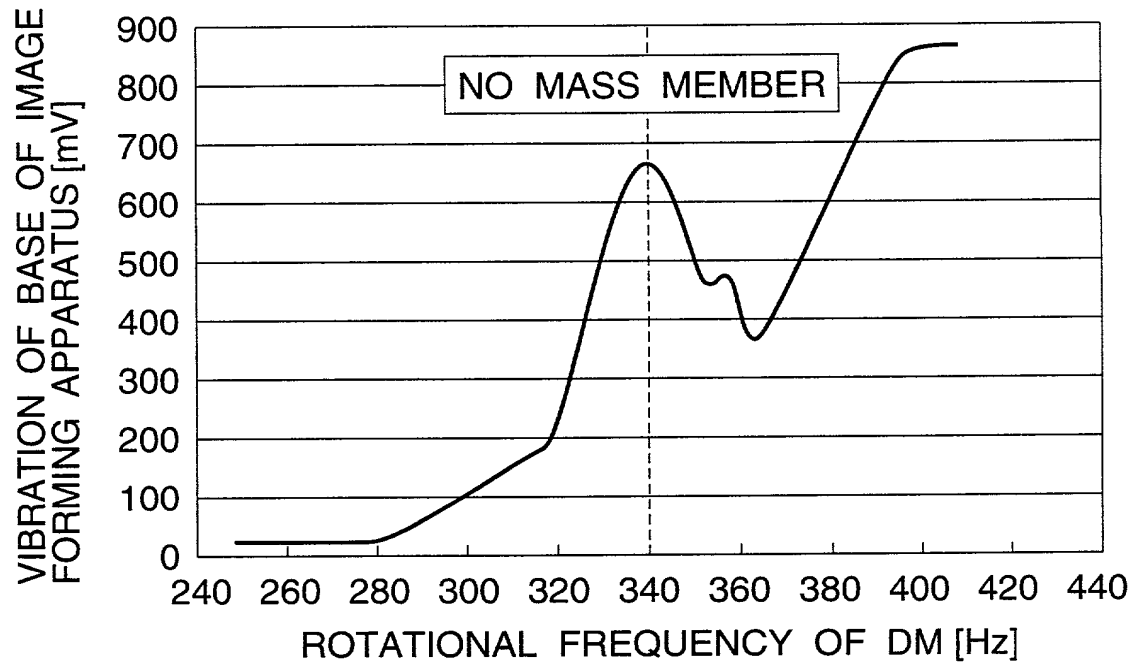


FIG.13

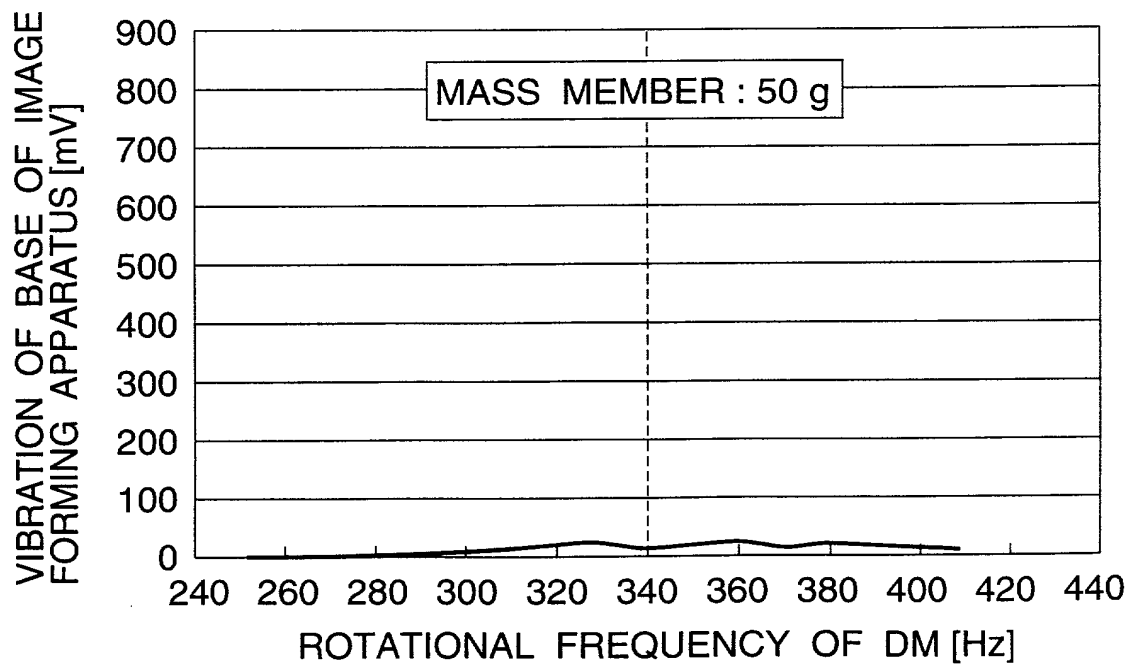


FIG.14A

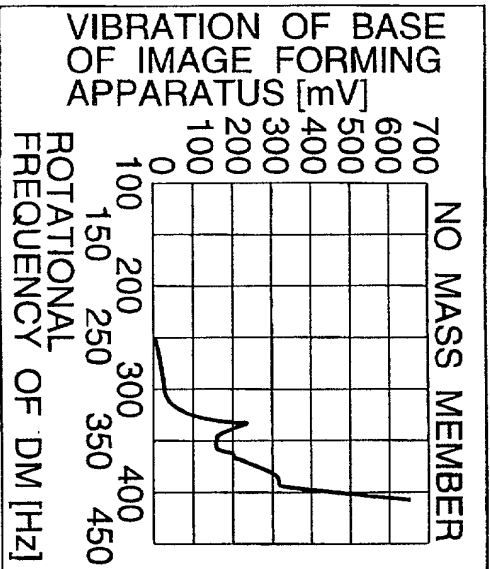


FIG.14B

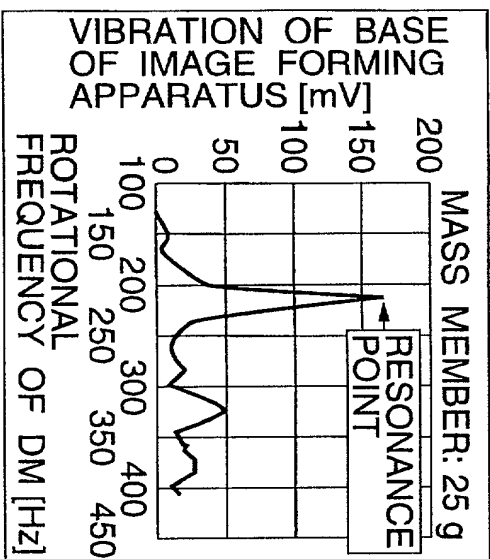


FIG.14C

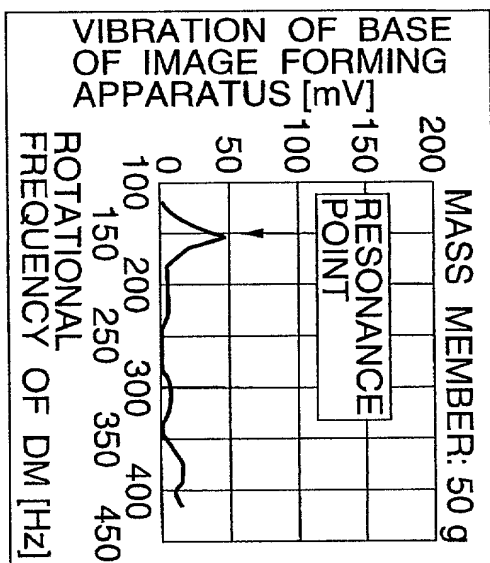


FIG.14D

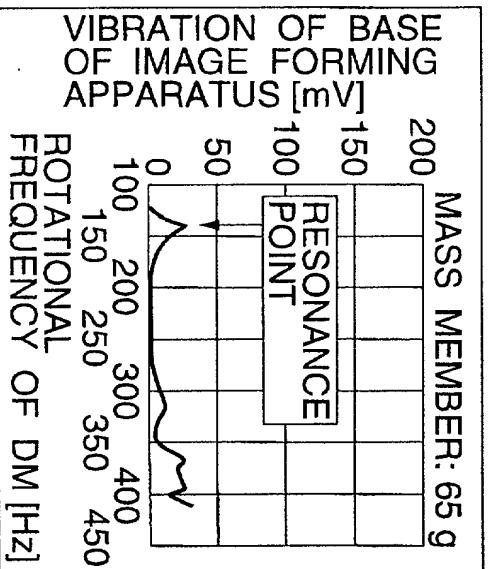


FIG.14E

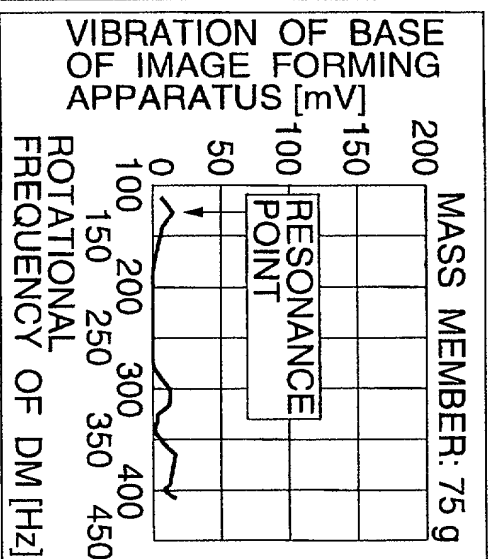


FIG.14F

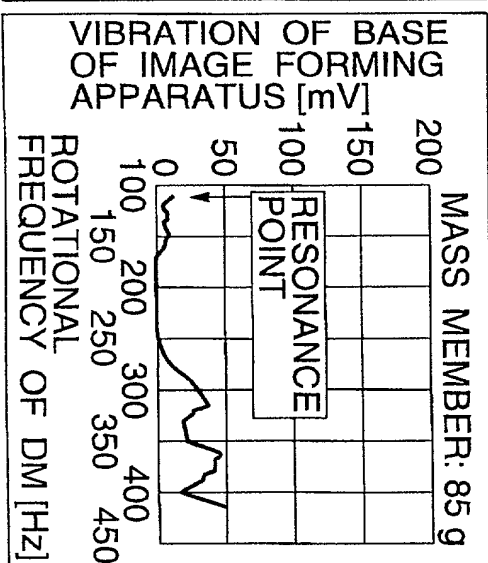


FIG.15

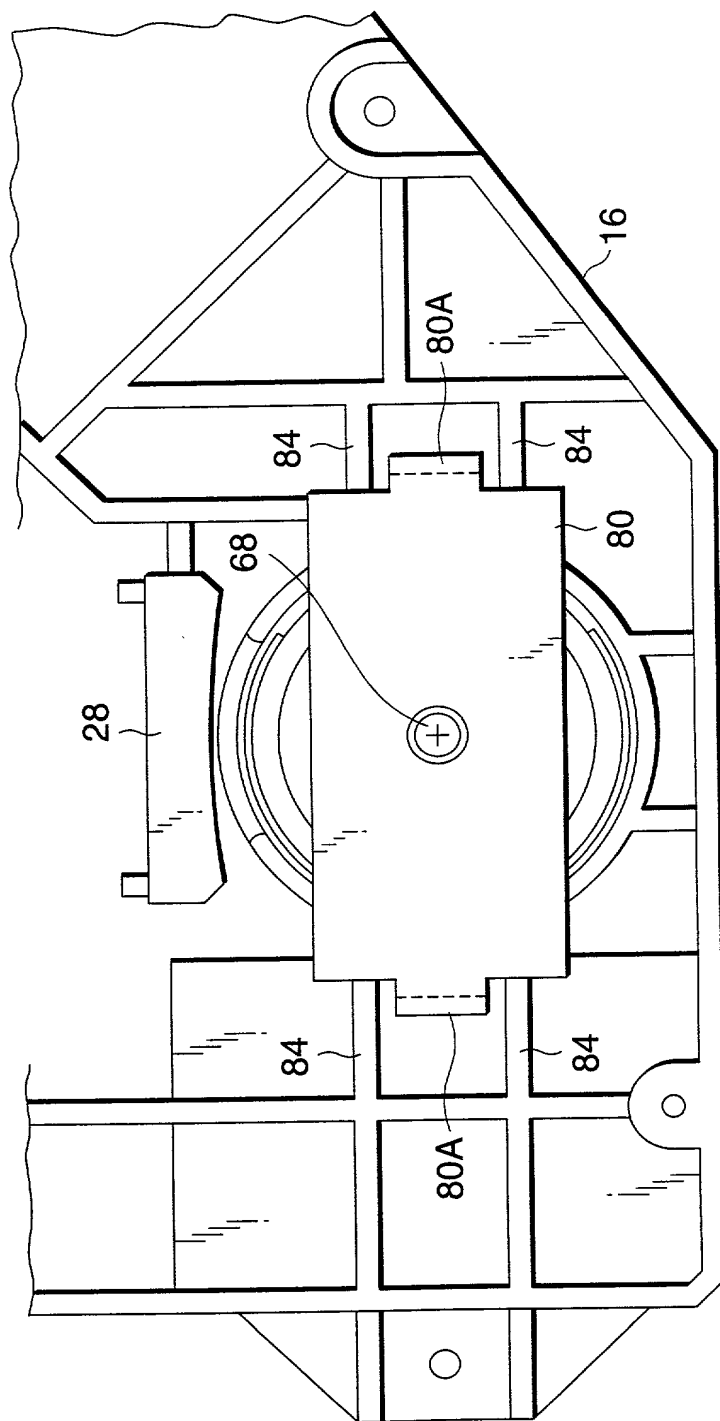




FIG.16

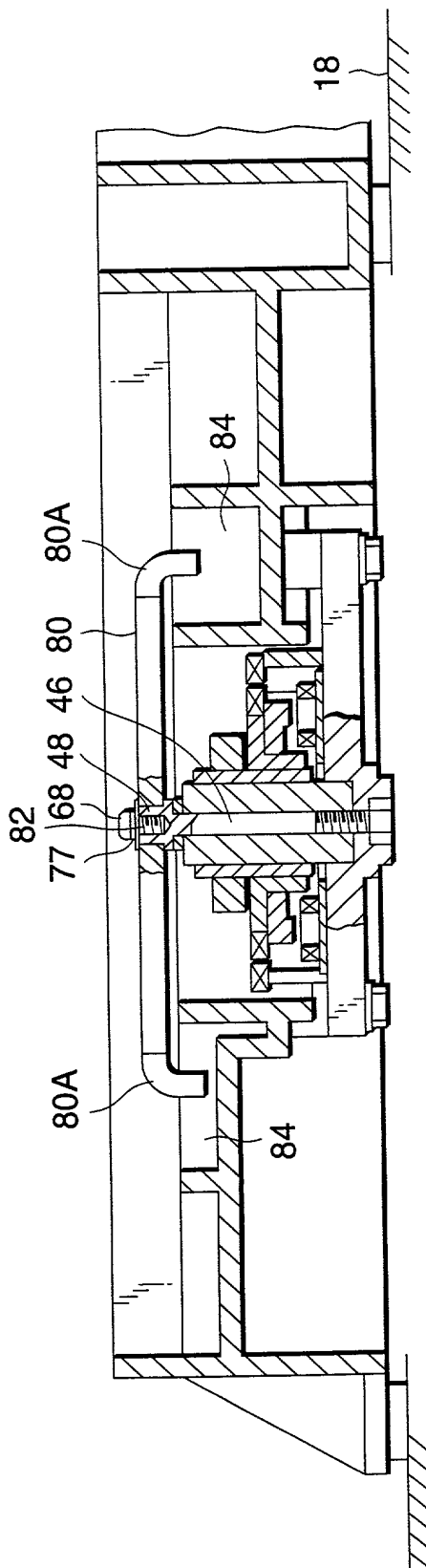


FIG.17A

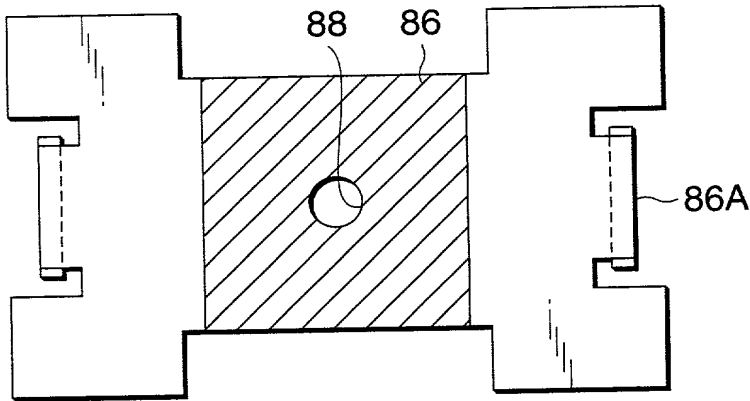


FIG.17B

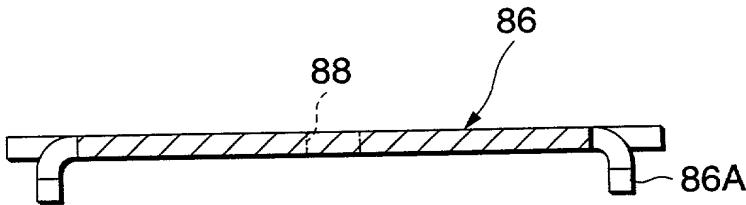


FIG.18A

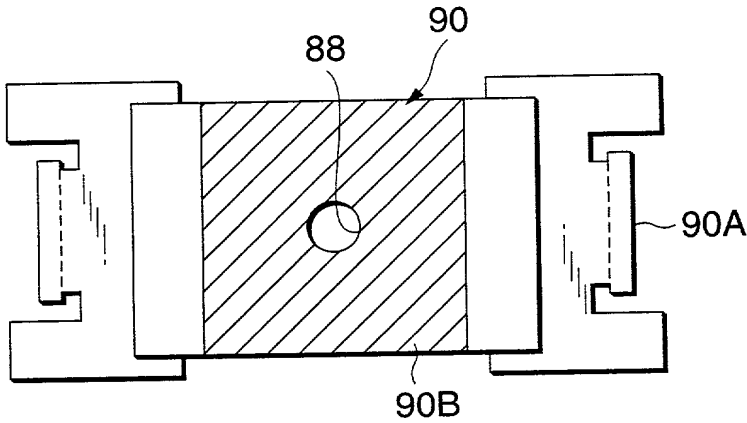


FIG.18B

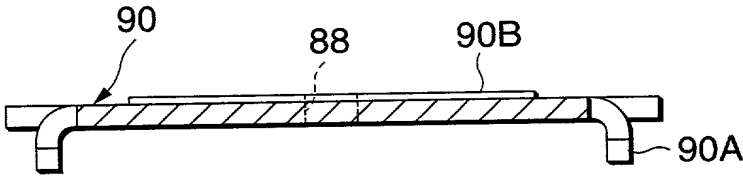


FIG.19A

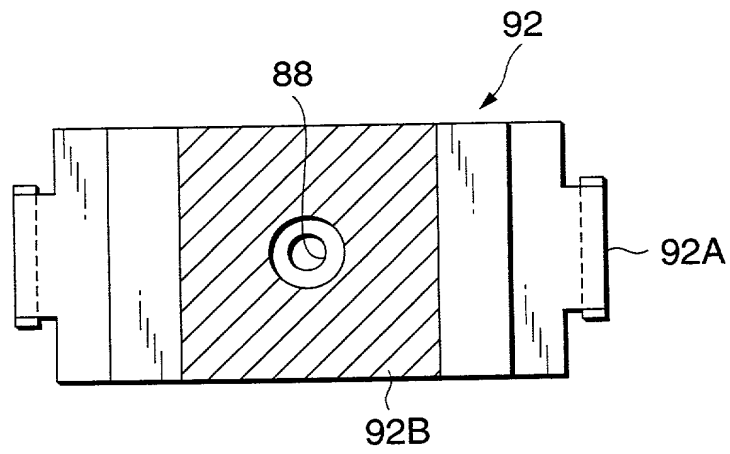


FIG.19B

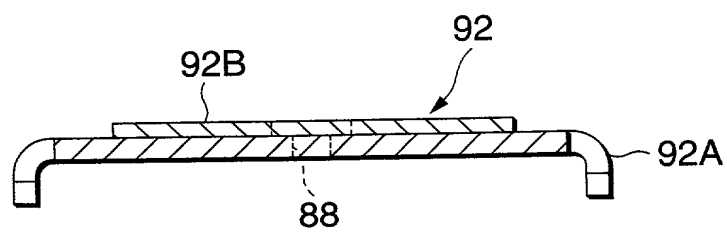


FIG.20

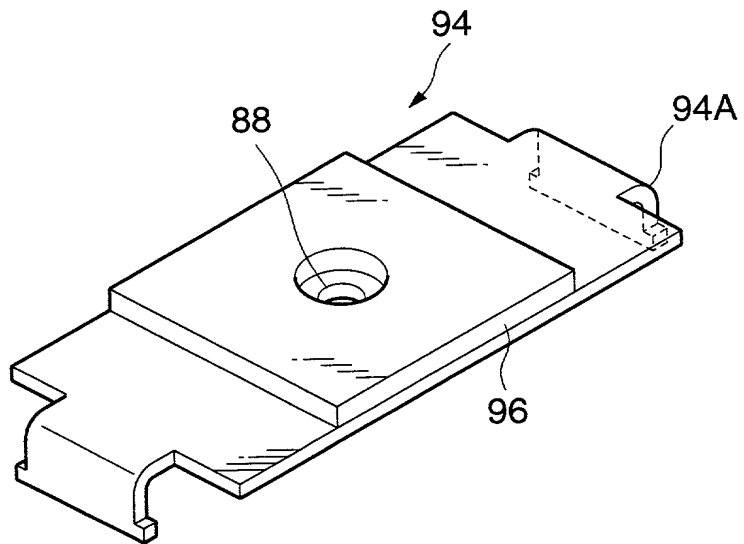


FIG.21A

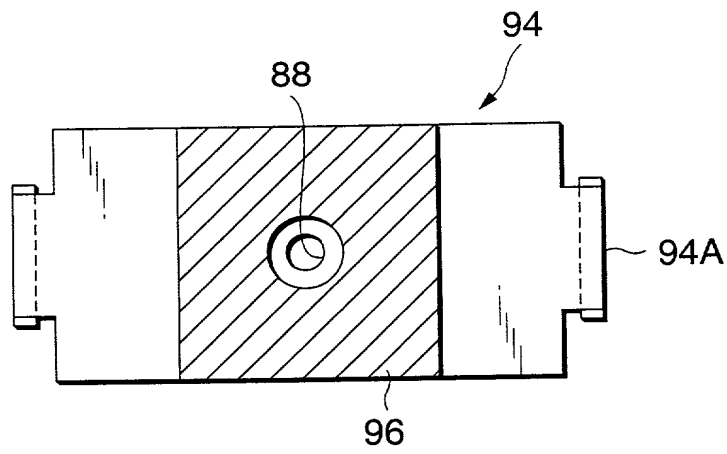


FIG.21B

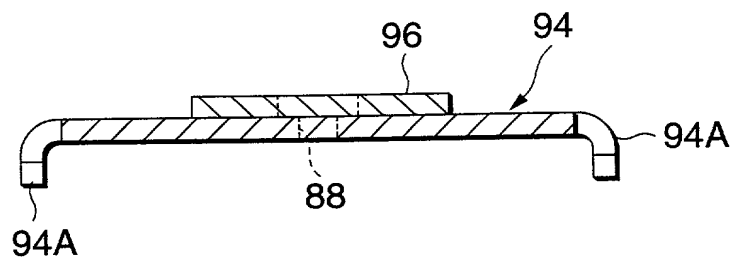


FIG.22

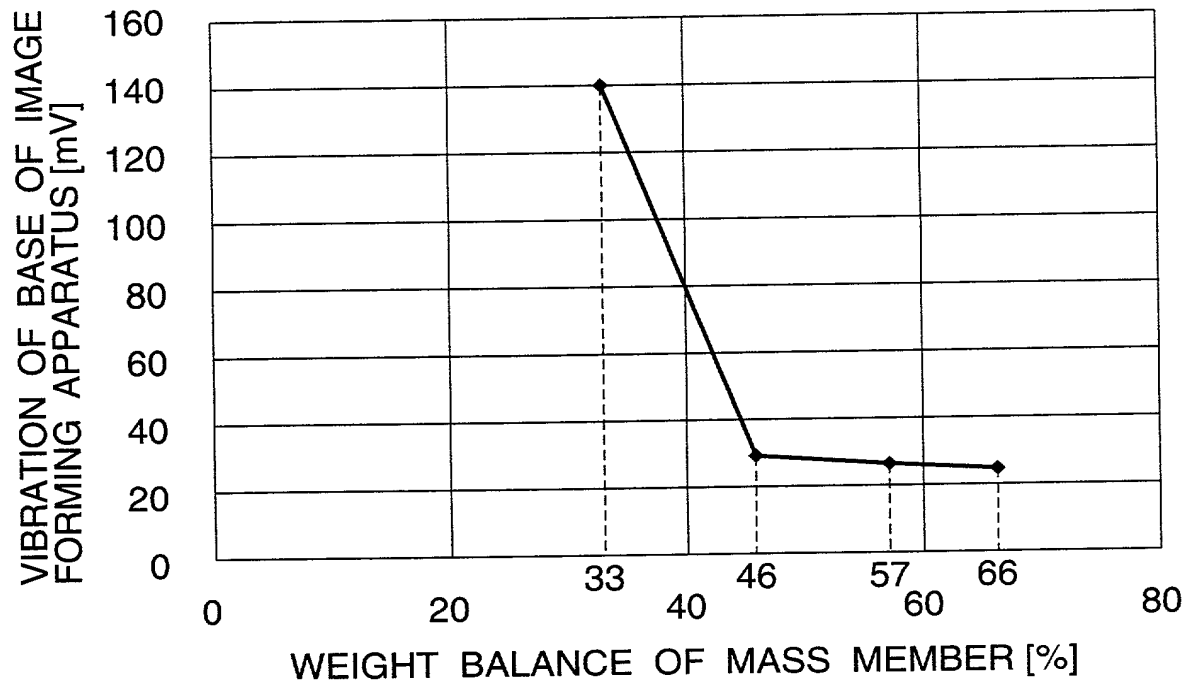


FIG.23

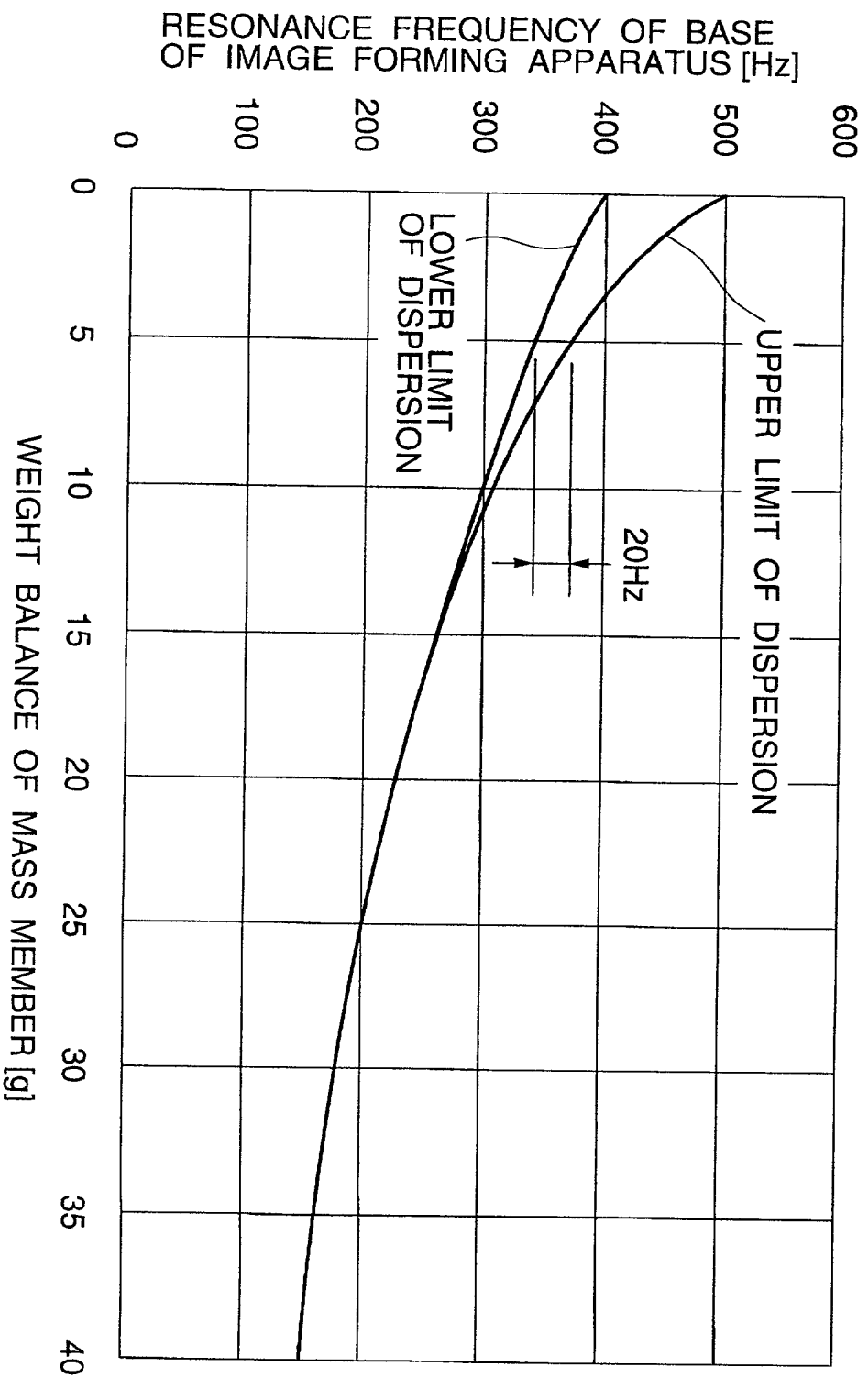




FIG.24

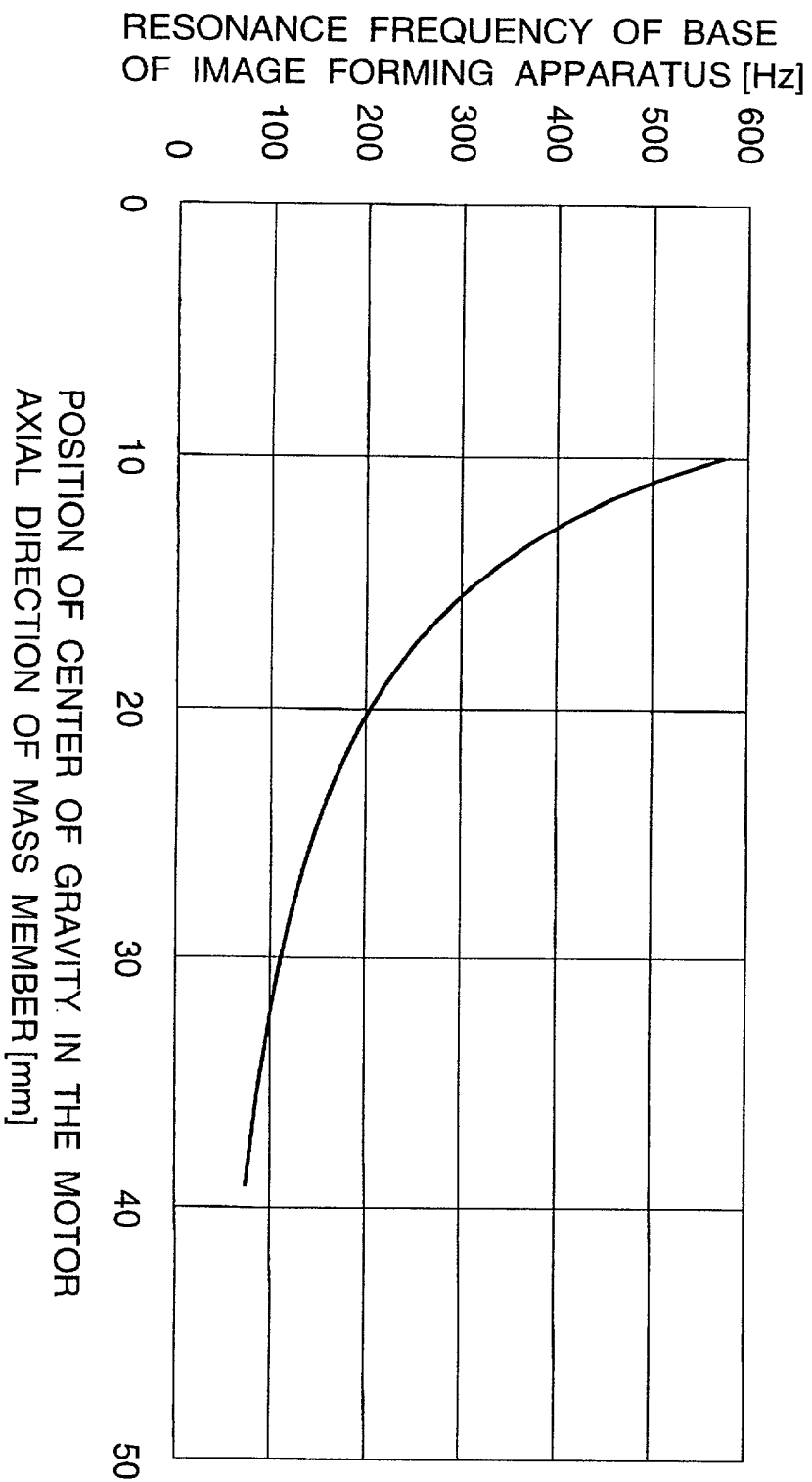


FIG.25

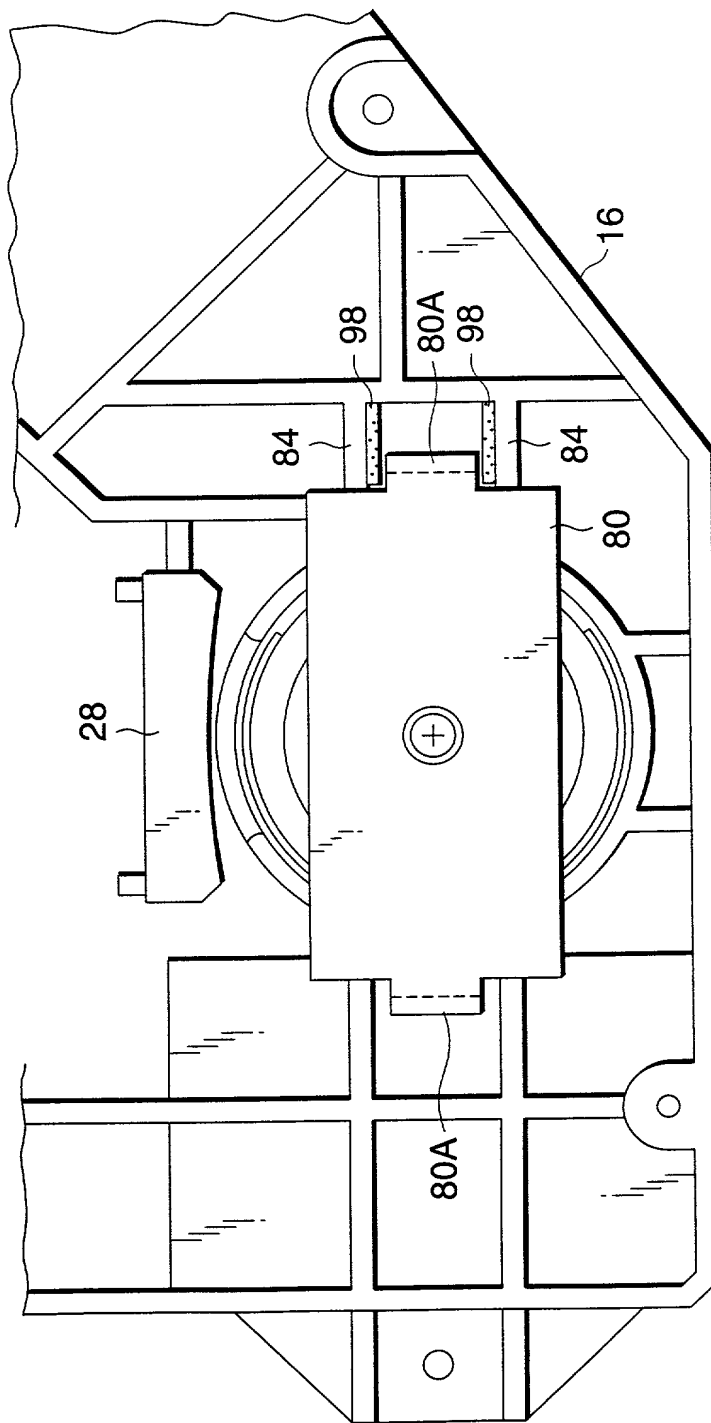


FIG.26

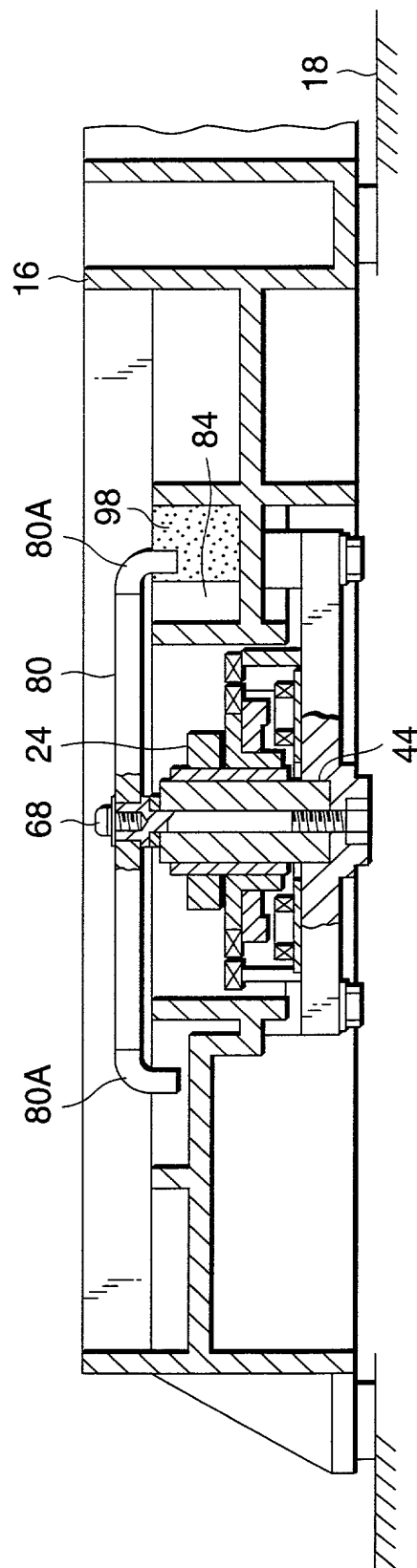


FIG.27

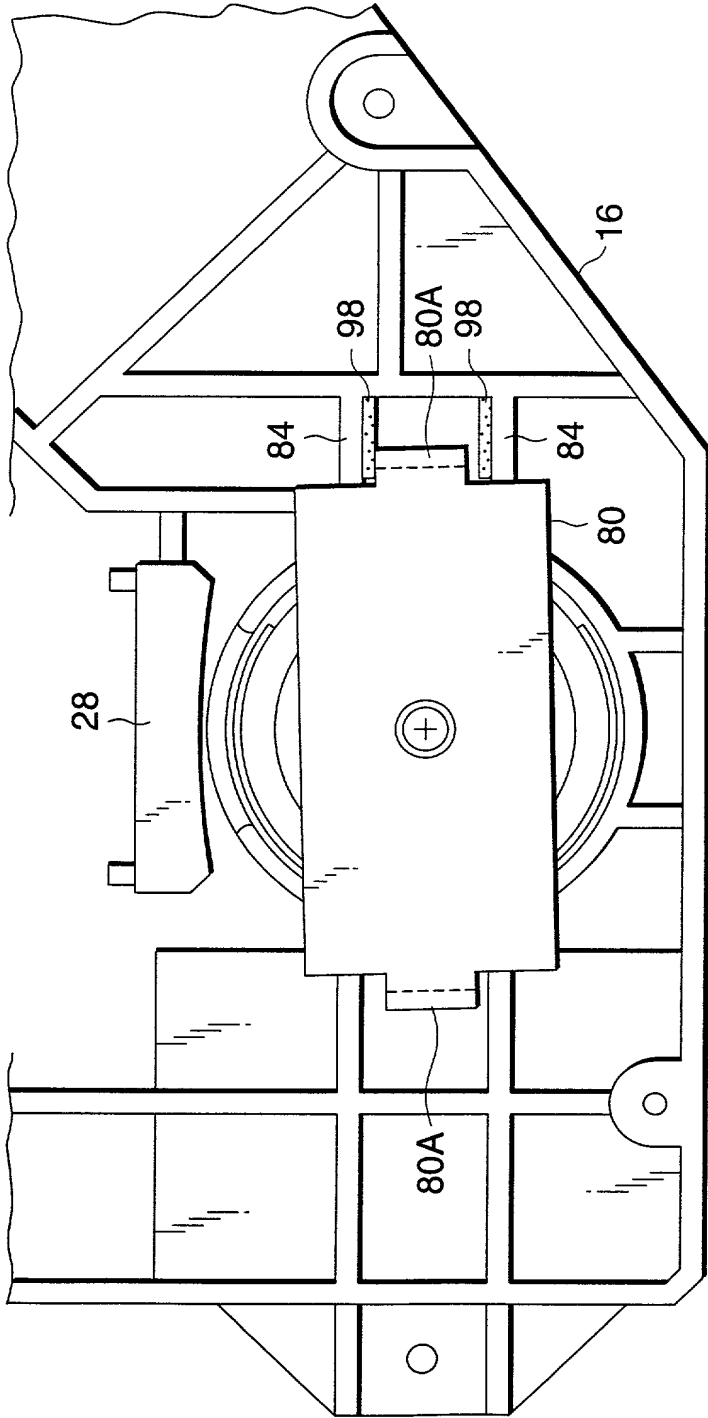
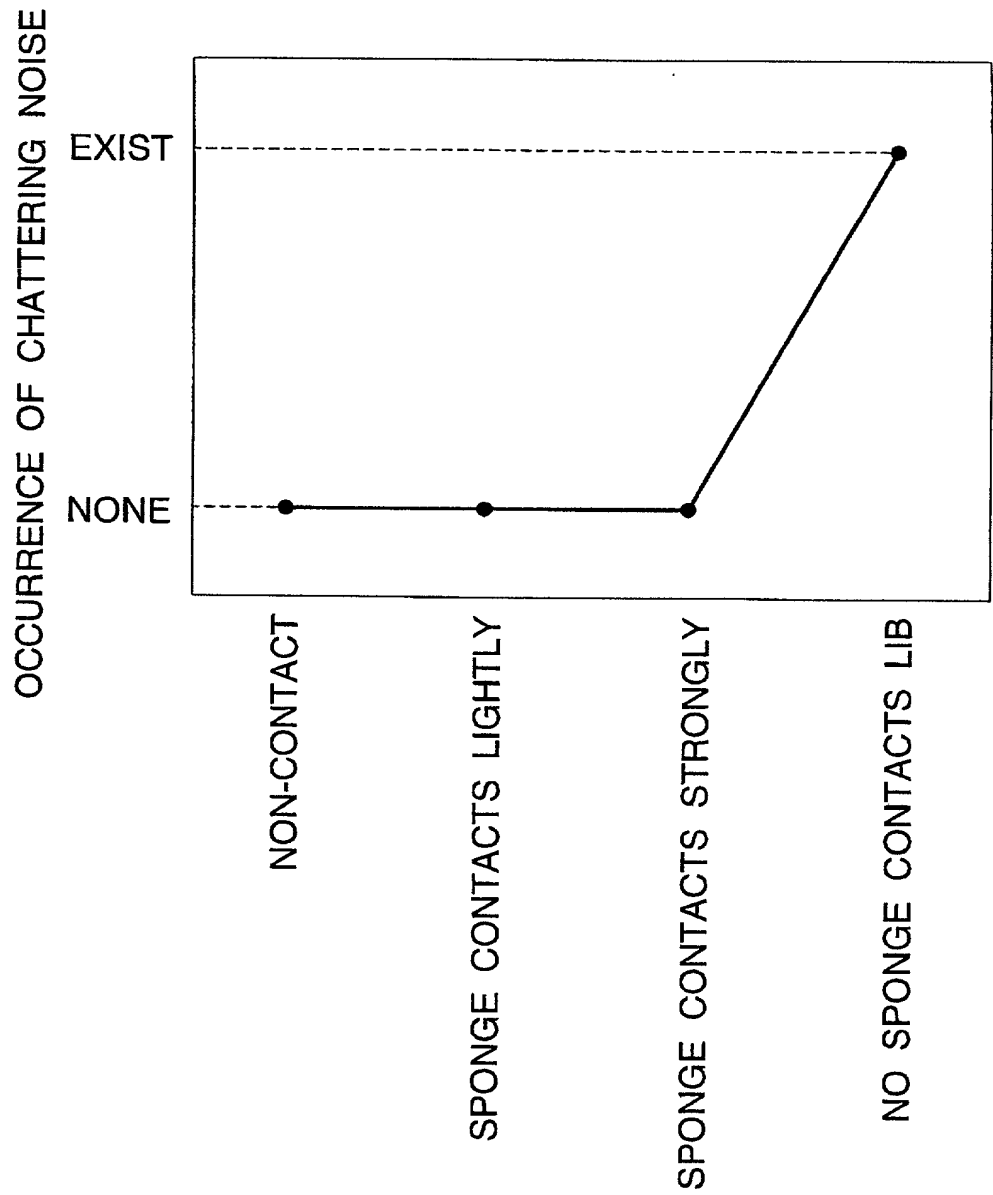


FIG.28



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FIG.29

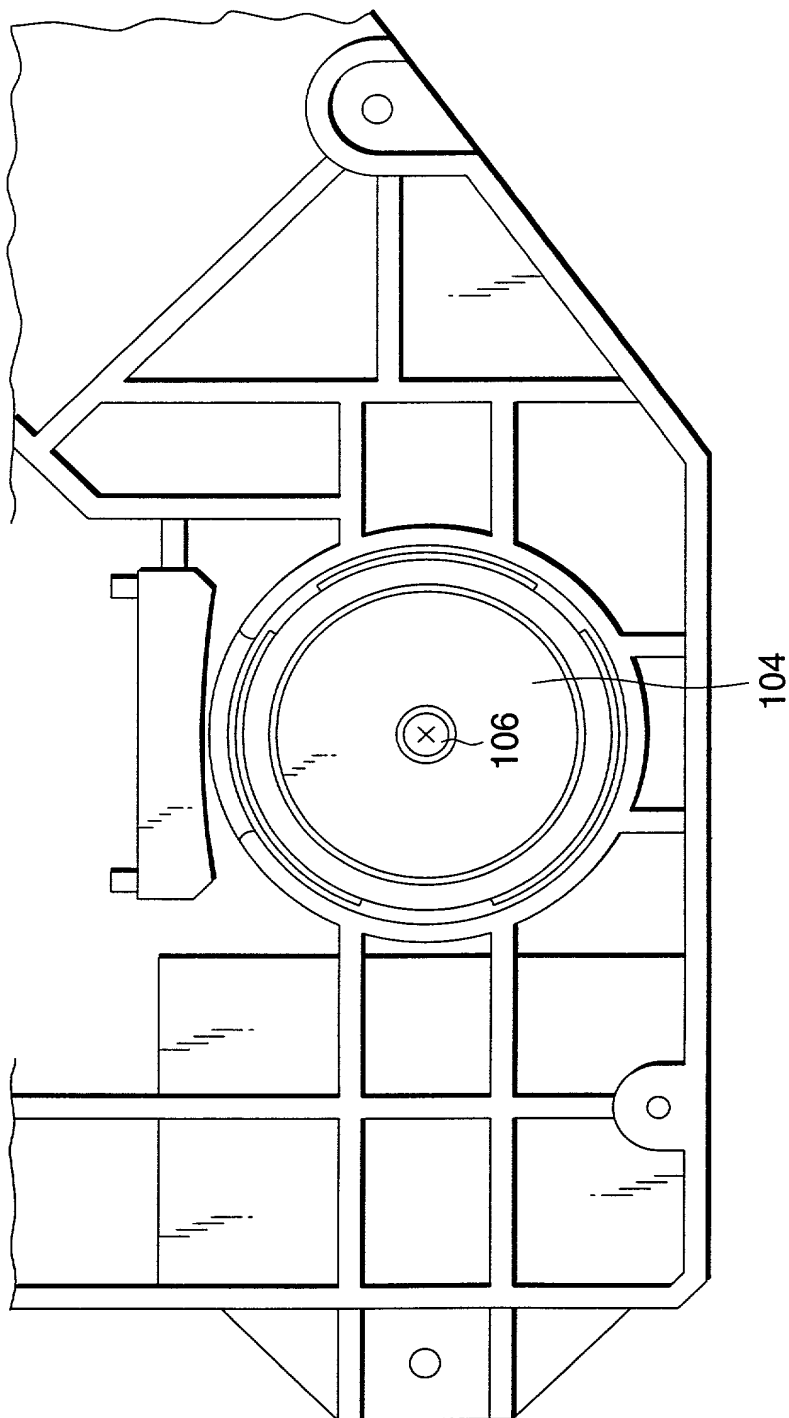
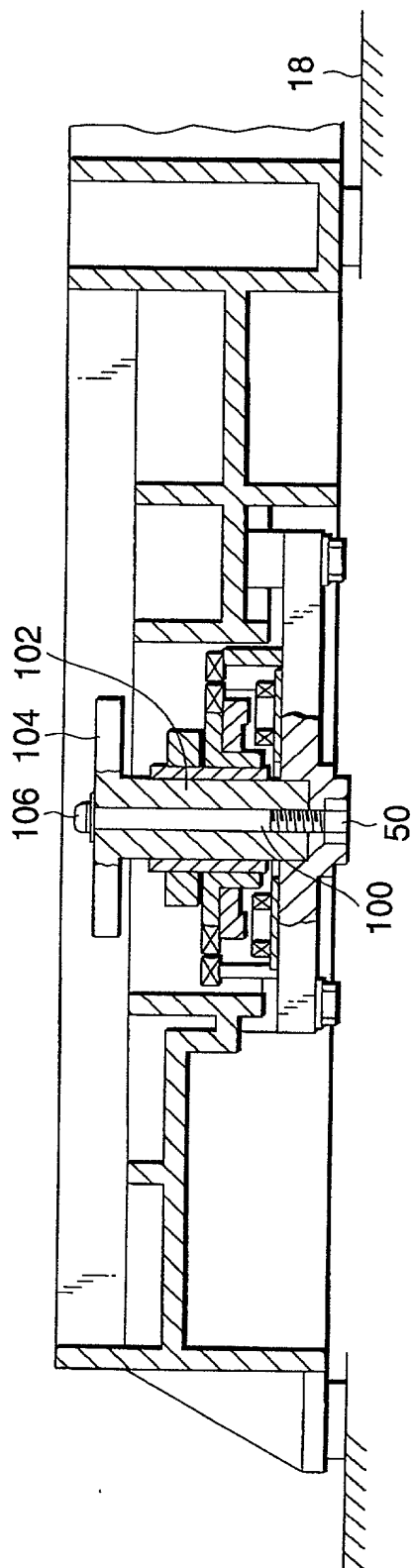


FIG.30



# APPLICATION FOR UNITED STATES PATENT DECLARATION AND POWER OF ATTORNEY

As a below named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name; that

I verily believe I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural inventors are named below) of the subject matter which is claimed and for which a patent is sought on the invention entitled:

ROTARY DEFLECTOR, OPTICAL SCANNING UNIT AND IMAGE FORMING APPARATUS

described and claimed in the specification:

Check one

- \*a. ☒ attached hereto.  
b. ☐ filed on \_\_\_\_\_ as Application Serial No. \_\_\_\_\_ and  
amended on \_\_\_\_\_  
(if applicable)

I hereby state that I have reviewed and understand the contents of the above-identified application, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose to the Office all information known to me to be material to patentability as defined in Title 37, Code of Federal Regulations, § 1.56.

Under Title 35 U.S. Code § 119, the priority benefits of the following foreign application(s) and/or United States provisional application(s) filed within one year prior to this application are hereby claimed:

Japanese Patent Application No. 11-255592, filed on September 9, 1999

The following application(s) for patent or inventor's certificate on this invention were filed in countries foreign to the United States of America either (a) more than one year prior to this application, or (b) before the filing date of the above-named foreign priority application(s) and/or United States provisional application(s):

As a named inventor, I hereby appoint the registered practitioners of Morgan, Lewis & Bockius LLP included in the Customer Number provided below to prosecute this application and to transact all business in the Patent and Trademark Office connected therewith, and direct that all correspondence be addressed to that Customer Number.

**Customer Number: 009629**

I hereby declare that I have reviewed and understand the contents of this Declaration, and that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

Typewritten Full Name  
of Sole or First inventor:

Masayoshi

Okura

Given Name

Middle Initial

Family Name

\*\*Inventor's Signature:

*Masayoshi*

*Okura*

\*\*Date of Signature:

6

16

2000

Month

Day

Year

Residence:

Ebina-shi

Kanagawa

Japan

City

State of Province

Country

Citizenship:

Japan

Post Office Address:

c/o Fuji Xerox Co., Ltd., 2274, Hongo,

(Insert complete mailing  
address, including country)

Ebina-shi, Kanagawa, Japan

\*This form may be executed only when attached to the specification (including claims) at the end thereof if Box a. is checked.

\*\*Note to Inventor: Please sign name exactly as it appears above and insert the actual date of signing.

IF THERE IS MORE THAN ONE INVENTOR USE PAGE 2 AND PLACE AN "X" HERE ☒

09613744-031100



# PAGE 2 OF U.S.A. DECLARATION FORM

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Kobayashi

\*\*Inventor's Signature:

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\*\*Date of Signature:

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*Kobayashi*

*6* / *12* / *2000*

Month

Day

Year

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State of Province

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Shao

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\*\*Date of Signature:

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*6* / *12* / *2000*

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Otsu

\*\*Inventor's Signature:

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Middle Initial

Family Name

\*\*Date of Signature:

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*6* / *12* / *2000*

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Ebina-shi, Kanagawa, Japan

Typewritten Full Name  
of Fifth Joint inventor:

Given Name

Middle Initial

Family Name

\*\*Inventor's Signature:

\*\*Date of Signature:

Month

Day

Year

Residence:

City

State of Province

Country

Citizenship:

Post Office Address:

(Insert Complete mailing  
address, including country)

\*\*Note to Inventors: Please sign name exactly as it appears and insert the actual date of signing.

This form may be executed only when attached to the first page of the Declaration and Power of Attorney form of the application to which it pertains.

2007-03-24 14:36:50